
Algorithm 1 LEARN($(\Delta_p, \Delta_n), H$)

Input: multi-relational dataset (Δ_p, Δ_n) and hyperparameters $H = \{D, \gamma, \gamma', C_e, C_n, T, \alpha_0\}$.

Output: model (A, R) .

Initialize: randomly initialize A, R to satisfy Eqs. (1) and (2), and set $\bar{A} = A, \bar{R} = R, t = 1, \alpha = \alpha_0$.

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1: repeat
2:   Sample  $v \sim \text{Bernoulli}(0.5)$ 
3:   if  $v = 1$  then
4:     Sample  $t_p = (i_p, j_p, k_p)$  from  $\Delta_p$  and  $\bar{t}_p = (\bar{i}_p, \bar{j}_p, \bar{k}_p)$ 
       from  $\Delta \setminus \Delta_p$ .
5:     Compute indicators as
       
$$I_1 \leftarrow H \left( \gamma - \mathbf{a}_{i_p}^\top R_{k_p} \mathbf{a}_{j_p} + \mathbf{a}_{\bar{i}_p}^\top R_{\bar{k}_p} \mathbf{a}_{\bar{j}_p} \right),$$

       
$$I_2 \leftarrow H \left( \gamma' - \mathbf{a}_{i_p}^\top R_{k_p} \mathbf{a}_{j_p} \right).$$

6:     Update model parameters as
       
$$\mathbf{a}_{i_p} \leftarrow \mathbf{a}_{i_p} - \alpha \left[ -(I_1 + I_2 C_e) \bar{R}_{k_p} \bar{\mathbf{a}}_{j_p} \right],$$

       
$$\mathbf{a}_{j_p} \leftarrow \mathbf{a}_{j_p} - \alpha \left[ -(I_1 + I_2 C_e) \bar{R}_{k_p}^\top \bar{\mathbf{a}}_{i_p} \right],$$

       
$$R_{k_p} \leftarrow R_{k_p} - \alpha \left[ -(I_1 + I_2 C_e) \bar{\mathbf{a}}_{i_p} \bar{\mathbf{a}}_{j_p}^\top \right],$$

       
$$\mathbf{a}_{\bar{i}_p} \leftarrow \mathbf{a}_{\bar{i}_p} - \alpha \left[ I_1 \bar{R}_{\bar{k}_p} \bar{\mathbf{a}}_{\bar{j}_p} \right],$$

       
$$\mathbf{a}_{\bar{j}_p} \leftarrow \mathbf{a}_{\bar{j}_p} - \alpha \left[ I_1 \bar{R}_{\bar{k}_p}^\top \bar{\mathbf{a}}_{\bar{i}_p} \right],$$

       
$$R_{\bar{k}_p} \leftarrow R_{\bar{k}_p} - \alpha \left[ I_1 \bar{\mathbf{a}}_{\bar{i}_p} \bar{\mathbf{a}}_{\bar{j}_p}^\top \right].$$

7:   else if  $v = 0$  then
8:     Sample  $t_n = (i_n, j_n, k_n)$  from  $\Delta_n$  and  $\bar{t}_n =$ 
        $(\bar{i}_n, \bar{j}_n, \bar{k}_n)$  from  $\Delta \setminus \Delta_n$ .
9:     Compute indicators as
       
$$I_3 \leftarrow H \left( \gamma - \mathbf{a}_{i_n}^\top R_{k_n} \mathbf{a}_{j_n} + \mathbf{a}_{\bar{i}_n}^\top R_{k_n} \mathbf{a}_{j_n} \right),$$

       
$$I_4 \leftarrow H \left( \gamma' + \mathbf{a}_{i_n}^\top R_{k_n} \mathbf{a}_{j_n} \right).$$

10:    Update model parameters as
       
$$\mathbf{a}_{i_n} \leftarrow \mathbf{a}_{i_n} - \alpha \left[ (I_3 C_n + I_4 C_e) \bar{R}_{k_n} \bar{\mathbf{a}}_{j_n} \right],$$

       
$$\mathbf{a}_{j_n} \leftarrow \mathbf{a}_{j_n} - \alpha \left[ (I_3 C_n + I_4 C_e) \bar{R}_{k_n}^\top \bar{\mathbf{a}}_{i_n} \right],$$

       
$$R_{k_n} \leftarrow R_{k_n} - \alpha \left[ (I_3 C_n + I_4 C_e) \bar{\mathbf{a}}_{i_n} \bar{\mathbf{a}}_{j_n}^\top \right],$$

       
$$\mathbf{a}_{\bar{i}_n} \leftarrow \mathbf{a}_{\bar{i}_n} - \alpha \left[ -I_3 C_n \bar{R}_{\bar{k}_n} \bar{\mathbf{a}}_{\bar{j}_n} \right],$$

       
$$\mathbf{a}_{\bar{j}_n} \leftarrow \mathbf{a}_{\bar{j}_n} - \alpha \left[ -I_3 C_n \bar{R}_{\bar{k}_n}^\top \bar{\mathbf{a}}_{\bar{i}_n} \right],$$

       
$$R_{\bar{k}_n} \leftarrow R_{\bar{k}_n} - \alpha \left[ -I_3 C_n \bar{\mathbf{a}}_{\bar{i}_n} \bar{\mathbf{a}}_{\bar{j}_n}^\top \right].$$

11:   end if
12:   for  $i \in \mathcal{E}$  such that  $\mathbf{a}_i \neq \bar{\mathbf{a}}_i$  do
13:      $\mathbf{a}_i \leftarrow \mathbf{a}_i / \|\mathbf{a}_i\|_2$ .
14:      $\bar{\mathbf{a}}_i \leftarrow \mathbf{a}_i$ .
15:   end for
16:   for  $k \in \mathcal{R}$  such that  $R_k \neq \bar{R}_k$  do
17:      $U_k, \Sigma_k, V_k \leftarrow \text{SVD}(R_k)$ .
18:      $R_k \leftarrow U_k V_k^*$ .
19:      $\bar{R}_k \leftarrow R_k$ .
20:   end for
21:    $\alpha \leftarrow \alpha_0 / \sqrt{t + 1}$ .
22:    $t \leftarrow t + 1$ .
23: until  $t \geq T$  holds.
24: return  $(A, R)$ 
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Algorithm 2 LEARNDEFAULT($(\Delta_p, \Delta_n), (\Delta_p^{(v)}, \Delta_n^{(v)}), \mathcal{H}$)

Input: training dataset (Δ_p, Δ_n) , validation dataset $(\Delta_p^{(v)}, \Delta_n^{(v)})$, and a set of models $\mathcal{H} = \{H^{(l)} \mid l \in \{1, \dots, L\}\}$.

Output: default model (A, R) .

```
1: for  $l = 1, \dots, L$  do
2:    $(A^{(l)}, R^{(l)}) \leftarrow \text{LEARN}(\Delta_p, \Delta_n, H^{(l)})$ .
3:    $v^{(l)} \leftarrow \text{VALSCORE}(A^{(l)}, R^{(l)}, \Delta_p^{(v)}, \Delta_n^{(v)})$ .
4: end for
5:  $l^* \leftarrow \arg \max_{l=1, \dots, L} v^{(l)}$ .
6: return  $(A^{(l^*)}, R^{(l^*)})$ .
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Algorithm 3 Active Multi-relational Data Construction

Input: budget $B > 0$, budget for validation $N_{\text{val}} > 0$, initial dataset $(\Delta_p^{(0)}, \Delta_n^{(0)})$, a set of hyperparameters $\mathcal{H} = \{H^{(l)} \mid l \in \{1, \dots, L\}\}$, the number of queries q , the number of unlabeled triples to calculate a query score Q , and a query score function.

Output: dataset (Δ_p, Δ_n) and model (A^*, R^*) .

Initialization:

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1:  $(\Delta_p, \Delta_n) \leftarrow (\Delta_p^{(0)}, \Delta_n^{(0)})$ .
2: Create a validation dataset of size  $N_{\text{val}}$ ,  $(\Delta_p^{(v)}, \Delta_n^{(v)})$ .
3:  $(A^*, R^*) \leftarrow \text{LEARNDEFAULT}((\Delta_p, \Delta_n), (\Delta_p^{(v)}, \Delta_n^{(v)}), \mathcal{H})$ .
4:  $t \leftarrow 0$ .
```

Main algorithm:

```
1: while  $tq \leq B$  do
2:   Randomly sample  $Q$  unlabeled triples to construct  $\Delta_u$ .
3:   for each triple  $t \in \Delta_u$  do
4:     Compute the query score  $q_t$  using the query score function.
5:   end for
6:   Choose  $q$  triples with the lowest query scores to construct  $\Delta_q^*$ .
7:   for each triple  $t \in \Delta_q^*$  do
8:      $l \leftarrow \mathcal{O}(t)$ .
9:     if  $l = 1$  then
10:       $\Delta_p \leftarrow \Delta_p \cup \{t\}$ .
11:     else
12:       $\Delta_n \leftarrow \Delta_n \cup \{t\}$ .
13:     end if
14:   end for
15:    $(A^*, R^*) \leftarrow \text{LEARNDEFAULT}((\Delta_p, \Delta_n), (\Delta_p^{(v)}, \Delta_n^{(v)}), \mathcal{H})$ .
16:    $t \leftarrow t + 1$ .
17: end while
18: return  $(\Delta_p, \Delta_n)$  and  $(A^*, R^*)$ .
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